

GARCH-M Model

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In finance, the return of a security may depend on its volatility (risk). To model such phenomena, the GARCH-in-mean (GARCH-M) model adds a heteroskedasticity term into the mean equation. It has the specification:
$$x_t = \mu + \lambda \sigma_t + a_t$$
$$\sigma_t^2 = \alpha_0 + \sum_{i=1}^p \alpha_i a_{t-i}^2 + \sum_{j=1}^q \beta_j \sigma_{t-j}^2$$
$$a_t = \sigma_t \epsilon_t$$
 where $\epsilon_t \sim P_{\nu}(0,1)$

- Where:
- x_t is the time series value at time t .
- μ is the mean of GARCH model.
- λ is the volatility coefficient (risk premium) for the mean.
- a_t is the model's residual at time t .
- σ_t is the conditional standard deviation (i.e. volatility) at time t .
- p is the order of the ARCH component model.
- $(\alpha_0, \alpha_1, \alpha_2, \dots, \alpha_p)$ are the parameters of the the ARCH component model.
- q is the order of the GARCH component model.
- $(\beta_1, \beta_2, \dots, \beta_q)$ are the parameters of the the GARCH component model.
- ϵ_t are the standardized residuals: $\epsilon_t \sim i.i.d$
 $E[\epsilon_t] = 0$ $VAR[\epsilon_t] = 1$
- P_{ν} is the probability distribution function for ϵ_t . Currently, the following distributions are supported:
 1. Normal distribution $P_{\nu} = N(0,1)$
 2. Student's t-distribution $P_{\nu} = t_{\nu}(0,1)$ $\nu \succ 4$
 3. Generalized error distribution (GED) $P_{\nu} = \mathit{GED}_{\nu}(0,1)$ $\nu \succ 1$

Remarks

1. A positive risk-premium (i.e. λ) indicates that data series is positively related to its volatility.
2. Furthermore, the GARCH-M model implies that there are serial correlations in the data series itself which were introduced by those in the volatility (σ_t^2) process.
3. The mere existence of risk-premium is, therefore, another reason that some historical stocks returns exhibit serial correlations.

See Also

[template("related")]