

# NDK\_GARCH\_PARAM

Last Modified on 07/12/2016 11:30 am CDT

- C/C++
- .Net

```
int __stdcall NDK_GARCH_PARAM(double * pData,
                               size_t  nSize,
                               double * mu,
                               double * Alphas,
                               size_t  p,
                               double * Betas,
                               size_t  q,
                               WORD  nInnovationType,
                               double * nu,
                               WORD  retType,
                               size_t  maxIter
                               )
```

Returns an array of cells for the initial (non-optimal), optimal or standard errors of the model's parameters.

## Returns

status code of the operation

## Return values

**NDK\_SUCCESS** Operation successful

**NDK\_FAILED** Operation unsuccessful. See [Macros](#) for full list.

## Parameters

- |          |                        |  |
|----------|------------------------|--|
| [in]     | <b>pData</b>           | is the univariate time series data (a one dimensional array).  |
| [in]     | <b>nSize</b>           | is the number of observations in pData.  |
| [in,out] | <b>mu</b>              | is the GARCH model conditional mean (i.e. mu).   |
| [in,out] | <b>Alphas</b>          | are the parameters of the ARCH(p) component model (starting with the lowest lag).                            |
| [in]     | <b>p</b>               | is the number of elements in Alphas array  |
| [in,out] | <b>Betas</b>           | are the parameters of the GARCH(q) component model (starting with the lowest lag).                           |
| [in]     | <b>q</b>               | is the number of elements in Betas array   |
| [in]     | <b>nInnovationType</b> | is the probability distribution function of the innovations/residuals (see <a href="#">INNOVATION_TYPE</a> ) |
- INNOVATION\_GAUSSIAN Gaussian Distribution (default)
  - INNOVATION\_TDIST Student's T-Distribution,
  - INNOVATION\_GED Generalized Error Distribution (GED)

[in,out] **nu** is the shape factor (or degrees of freedom) of the innovations/residuals probability distribution function.

[in] **retType** is a switch to select the type of value returned: 1= Quick Guess, 2=Calibrated, 3= Std. Errors ( see [MODEL\\_RETVAL\\_FUNC](#))

[in] **maxIter** is the maximum number of iterations used to calibrate the model. If missing or less than 100, the default maximum of 100 is assumed.

### Remarks

1. The underlying model is described [here](#).
2. The time series is homogeneous or equally spaced.
3. The time series may include missing values (e.g. #N/A) at either end.

### Requirements

<b>Header</b>	SFSDK.H
<b>Library</b>	SFSDK.LIB
<b>DLL</b>	SFSDK.DLL

```
int NDK_GARCH_PARAM(double[] pData,
                    UIntPtr nSize,
                    ref double mu,
                    double[] Alphas,
                    UIntPtr p,
                    double[] Betas,
                    UIntPtr q,
                    short nInnovationType,
                    ref double nu,
                    short retType,
                    UIntPtr maxIter
                    )
```

**Namespace:** NumXLAPI  
**Class:** SFSDK  
**Scope:** Public  
**Lifetime:** Static

Returns an array of cells for the initial (non-optimal), optimal or standard errors of the model's parameters.

### Return Value

a value from [NDK\\_RETCODE](#) enumeration for the status of the call.

**NDK\_SUCCESS** operation successful  
 Error                      Error Code

## Parameters

[in]	<b>pData</b>	is the univariate time series data (a one dimensional array).
[in]	<b>nSize</b>	is the number of observations in pData.
[in,out]	<b>mu</b>	is the GARCH model conditional mean (i.e. mu).
[in,out]	<b>Alphas</b>	are the parameters of the ARCH(p) component model (starting with the lowest lag).
[in]	<b>p</b>	is the number of elements in Alphas array
[in,out]	<b>Betas</b>	are the parameters of the GARCH(q) component model (starting with the lowest lag).
[in]	<b>q</b>	is the number of elements in Betas array
[in]	<b>nInnovationType</b>	is the probability distribution function of the innovations/residuals (see <b>INNOVATION_TYPE</b> ) <ul style="list-style-type: none"><li>• INNOVATION_GAUSSIAN Gaussian Distribution (default)</li><li>• INNOVATION_TDIST Student's T-Distribution,</li><li>• INNOVATION_GED Generalized Error Distribution (GED)</li></ul>
[in,out]	<b>nu</b>	is the shape factor (or degrees of freedom) of the innovations/residuals probability distribution function.
[in]	<b>retType</b>	is a switch to select the type of value returned: 1= Quick Guess, 2=Calibrated, 3= Std. Errors ( see <b>MODEL_RETVAL_FUNC</b> )
[in]	<b>maxIter</b>	is the maximum number of iterations used to calibrate the model. If missing or less than 100, the default maximum of 100 is assumed.

## Remarks

1. The underlying model is described [here](#).
2. The time series is homogeneous or equally spaced.
3. The time series may include missing values (e.g. #N/A) at either end.

## Exceptions

Exception Type	Condition
None	N/A

## Requirements

<b>Namespace</b>	NumXLAPI
<b>Class</b>	SFSDK
<b>Scope</b>	Public
<b>Lifetime</b>	Static

**Package**

NumXLAPI.DLL

## Examples

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## References

Hamilton, J .D.; [Time Series Analysis](#) , Princeton University Press (1994), ISBN 0-691-04289-6

Tsay, Ruey S.; [Analysis of Financial Time Series](#) John Wiley & SONS. (2005), ISBN 0-471-690740

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## See Also

[[template\("related"\)](#)]

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